

Simulation 15.06.2022 TASK 2 "Sensing & Mapping"

Team	Participated	Detected object during run (true positive)	Detected object during run (false positive)	Accuracy of mapped objects	Damaged plants	Total Task Points	Rank	Points
FREDT	<input type="checkbox"/>	0	0	0	0	0	N.R.	0
FloriBot	<input checked="" type="checkbox"/>	6	0	0	0	30	1	30
Robatic	<input checked="" type="checkbox"/>	0	0	0	0	0	4	25
Team Hohenheim	<input type="checkbox"/>	0	0	0	0	0	N.R.	0
Kamaro Engineering	<input checked="" type="checkbox"/>	6	0	0	1	26	2	28
Osnabrück Acorn	<input type="checkbox"/>	0	0	0	0	0	N.R.	0
FarmBeast	<input checked="" type="checkbox"/>	4	22	0	110	0	4	25
FH Münster	<input checked="" type="checkbox"/>	3	0	0	1	11	3	26
Camper Robotics	<input type="checkbox"/>	0	0	0	0	0	N.R.	0
Team HX	<input type="checkbox"/>	0	0	0	0	0	N.R.	0
Carbonite	<input checked="" type="checkbox"/>	0	0	0	0	0	4	25
AIRLab Polimi	<input checked="" type="checkbox"/>	0	0	0	20	0	4	25